# A uniqueness result for linear complementarity problems over the Jordan spin algebra 

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## A R T I C L E I N F O

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A B S T R A C T
Given a Euclidean Jordan algebra ( $V, \circ,\langle\cdot, \cdot\rangle$ ) with the (corresponding) symmetric cone $K$, a linear transformation $L: V \rightarrow V$ and $q \in V$, the linear complementarity problem $\mathrm{LCP}(L, q)$ is to find a vector $x \in V$ such that

$$
x \in K, \quad y:=L(x)+q \in K \text { and } x \circ y=0 .
$$

To investigate the global uniqueness of solutions in the setting of Euclidean Jordan algebras, the $P$-property and its variants of a linear transformation were introduced in Gowda et al. (2004) [3] and it is shown that if $\operatorname{LCP}(L, q)$ has a unique solution for all $q \in V$, then $L$ has the $P$-property but the converse is not true in general. In the present paper, when $(V, \circ,\langle\cdot, \cdot\rangle)$ is the Jordan spin algebra, we show that $\operatorname{LCP}(L, q)$ has a unique solution for all $q \in V$ if and only if $L$ has the $P$-property and $L$ is positive semidefinite on the boundary of $\mathcal{K}$.
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## 1. Introduction

For $n>1$, consider $\mathbb{R}^{n}$ with the usual inner-product $\langle x, y\rangle:=x^{T} y$. We write a vector $x$ in $\mathbb{R}^{n}$ by $\left[x_{0}, \bar{x}\right]^{T}$, where $x_{0} \in \mathbb{R}$ and define the Jordan product of any two $n$-vectors $x$ and $y$ by

$$
x \circ y:=\left[\begin{array}{c}
x^{T} y \\
x_{0} \bar{y}+y_{0} \bar{x}
\end{array}\right] .
$$

The triple $\left(\mathbb{R}^{n}, \circ,\langle\cdot, \cdot\rangle\right)$ is called Jordan-spin algebra. The cone of squares

$$
\mathcal{K}^{n}:=\left\{x \in \mathbb{R}^{n}: x_{0} \geq 0, \quad \bar{x}^{T} \bar{x} \leq x_{0}^{2}\right\}=\left\{x \circ x: x \in \mathbb{R}^{n}\right\}
$$

is the well-known second-order cone or the Lorentz cone. The most interesting case happens when $\mathcal{K}^{n}$ is non-polyhedral which is true iff $n>2$. Henceforth, we fix $n>2$ and simply use $\mathcal{K}$ to denote $\mathcal{K}^{n}$. Given an $n \times n$ real matrix $M$ and a vector $q$ in $\mathbb{R}^{n}$, the second-order cone linear complementarity problem $\operatorname{SOLCP}(M, q)$ is to find a vector $x \in \mathbb{R}^{n}$ such that

$$
x \in \mathcal{K}, \quad y:=M x+q \in \mathcal{K} \text { and } x \circ y=0\left(\Leftrightarrow x^{T} y=0\right)
$$

Complementarity problems appear in various areas that include game theory, optimization and economics. SOLCP is a classical example of a linear complementarity problem defined on a non-polyhedral cone. The Jordan spin algebra associated with the secondorder cone has rank two and has extra properties which allow us to go beyond the general study of complementarity problems. The text of Faraut and Koranyi [2] covers the foundations of Euclidean Jordan algebra.

Definition 1. We will say that an $n \times n$ real matrix $M$ has the Globally Uniquely Solvable (GUS) property, if $\operatorname{SOLCP}(M, q)$ has a unique solution for all $q \in \mathbb{R}^{n}$.

In general it is very difficult to verify whether a linear transformation has the GUS-property. Investigations on GUS-property of a linear transformation in Euclidean Jordan algebras are found in Gowda and Sznajder [4]. One of the fundamental problems in SOLCP is to find conditions that characterize the GUS-property of an $n \times n$ matrix. The problem can be posed in a more general setting.

Given a finite dimensional real Hilbert space $\mathcal{H}$, and a closed convex cone $\mathcal{C}$ in $\mathcal{H}$, a linear transformation $T: \mathcal{H} \rightarrow \mathcal{H}$, and a vector $q \in \mathcal{H}$, the (cone) linear complementarity problem $\operatorname{LCP}(T, \mathcal{H}, \mathcal{C})$ is to find a vector $x \in \mathcal{H}$ such that

$$
x \in \mathcal{C}, \quad y:=T x+q \in \mathcal{C}^{*} \quad \text { and }\langle x, y\rangle=0
$$

where $\mathcal{C}^{*}$, called the dual cone, is defined by

$$
\mathcal{C}^{*}:=\{u \in \mathcal{H}:\langle u, z\rangle \geq 0 \forall z \in \mathcal{C}\} .
$$

By specializing $\mathcal{H}=\mathbb{R}^{n}$ and $\mathcal{C}=\mathcal{K}$ with the usual inner-product, we get SOLCP. When $H=\mathbb{R}^{n}, C=\mathbb{R}^{n}+$ (the non-negative orthant) and $\langle x, y\rangle$ is the usual inner product, the above complementarity problem reduces, for an $n \times n$ matrix $M$, to the linear complementarity problem $\operatorname{LCP}(M, q)$ : Find $x \in \mathbb{R}^{n}$ such that

$$
\begin{equation*}
x \geq 0, \quad y:=M x+q \geq 0 \quad \text { and } x^{T} y=0 \tag{1}
\end{equation*}
$$

where the inequalities are defined in the component-wise sense. With numerous applications to many fields, see (Cottle, Pang and Stone [1]), the study of linear complementarity problem has received wide attention. In the LCP theory, the uniqueness of solution in $\operatorname{LCP}(M, q)$ for all $q$ is addressed via the following equivalent conditions [Theorems 3.3.4 and 3.3.7 in Cottle, Pang and Stone [1]]:
(P1) Every principal minor of $M$ is positive.
(P2) The implication

$$
x \in \mathbb{R}^{n}, \quad x * M x \leq 0 \Longrightarrow x=0
$$

holds, where $x * M x$ is the component-wise product of vectors $x$ and $M x$.
(P3) For every $q \in \mathbb{R}^{n}, \operatorname{LCP}(M, q)$ has a unique solution.

Generalizing (P2), Gowda et al. [3] introduced $P$-property for a linear transformation in a Euclidean Jordan algebra. However, in a non-polyhedral setting, it turns out that GUS and $P$-properties are not equivalent in general. Our findings in this paper are given below.

- The following are equivalent for an $n \times n$ matrix $M$.

1. $\operatorname{SOLCP}(M, q)$ has a unique solution for all $q \in \mathbb{R}^{n}$.
2. (a) $M$ has the $P$-property on $\mathcal{K}$.
(b) $x^{T} M x \geq 0$ and $x^{T} M^{-1} x \geq 0 \forall x \in \partial \mathcal{K}$.
3. (a) $M^{T}$ has the $P$-property on $\mathcal{K}$.
(b) $x^{T} M x \geq 0$ and $x^{T} M^{-1} x \geq 0 \forall x \in \partial \mathcal{K}$.

- If $M$ has $P$-property on $\mathcal{K}$, then $M^{T}$ need not have $P$-property on $\mathcal{K}$.
- If $A$ is a $\mathbf{Z}$-matrix with respect to $\mathcal{K}$, then the following are equivalent:
(i) $\operatorname{SOLCP}(A, q)$ has a unique solution for all $q \in \mathbb{R}^{n}$.
(ii) $A$ is positive stable and $x^{T} A x \geq 0$ for all $x \in \partial \mathcal{K}$.


### 1.1. Notations

(i) To denote the topological interior and the boundary of $\mathcal{K}$, we use $\operatorname{int}(\mathcal{K})$ and $\partial \mathcal{K}$ respectively.
(ii) Let $J$ denote the $n \times n$ diagonal matrix $\operatorname{diag}(1,-1,-1, \ldots,-1)$ and $e$ denote the vector $(1,0, \ldots, 0)^{T}$ in $\mathbb{R}^{n}$.
(iii) $\mathcal{C}(A)$ and $\mathcal{N}(A)$ will denote the column-space and null-space of a matrix $A$.
(iv) If $M$ is an $n \times n$ matrix and $\tau \in \mathbb{R}$, we define $M_{\tau}:=M-\tau J$.

### 1.2. Properties of Jordan spin algebra

Let $x \in \mathbb{R}^{n}$ and $y \in \mathbb{R}^{n}$ be written as

$$
x=\left[\begin{array}{c}
x_{0} \\
\bar{x}
\end{array}\right], \quad y=\left[\begin{array}{c}
y_{0} \\
\bar{y}
\end{array}\right] \quad\left(x_{0}, y_{0} \in \mathbb{R}\right) .
$$

(PR1) Recall that for any two vectors $x$ and $y$, the Jordan spin algebra is defined by:

$$
x \circ y:=\left[\begin{array}{c}
x^{T} y \\
x_{0} \bar{y}+y_{0} \bar{x}
\end{array}\right] .
$$

The following are immediate.
(a) $\mathcal{K}=\left\{x \circ x: x \in \mathbb{R}^{n}\right\}$.
(b) Let $u, v, w \in \mathbb{R}^{n}$ and $\alpha, \beta \in \mathbb{R}$. The following distributive law holds:

$$
\begin{aligned}
& u \circ(\alpha v+\beta w)=\alpha u \circ v+\beta u \circ w \\
& (\alpha v+\beta w) \circ u=\alpha v \circ u+\beta w \circ u .
\end{aligned}
$$

(PR2) Any pair of non-zero vectors $\left\{c_{1}, c_{2}\right\}$ that satisfy the following conditions is called a Jordan frame.
(S1) $c_{1} \circ c_{2}=0$.
(S2) $c_{1} \circ c_{1}=c_{1}$ and $c_{2} \circ c_{2}=c_{2}$.
(S3) $c_{1}+c_{2}=e$.
(PR3) Spectral decomposition: Let $x \in \mathbb{R}^{n}$. Then there exist real numbers $\lambda_{1}$ and $\lambda_{2}$ and a Jordan frame $\left\{c_{1}, c_{2}\right\}$ such that

$$
x=\lambda_{1} c_{1}+\lambda_{2} c_{2} .
$$

The following can be verified easily:
(i) $x \in \partial \mathcal{K}$ if and only if $\lambda_{1} \geq 0, \lambda_{2} \geq 0$ and $\lambda_{1} \lambda_{2}=0$.
(ii) $x \in \operatorname{int}(\mathcal{K})$ if and only if $\lambda_{1}>0$ and $\lambda_{2}>0$.
(PR4) Given a vector $x \in \mathbb{R}^{n}$, with the spectral decomposition $x=\lambda_{1} c_{1}+\lambda_{2} c_{2}$, we define the determinant of $x$ by $\operatorname{det}(x):=\lambda_{1} \lambda_{2}$. It is easy to verify the following:
(a) $\operatorname{det}(x)=0 \Longleftrightarrow x \in \partial \mathcal{K} \cup-\partial \mathcal{K} \Longleftrightarrow x_{0}^{2}=\|\bar{x}\|^{2}$.
(b) $\operatorname{det}(x)>0 \Longleftrightarrow x \in \operatorname{int}(\mathcal{K}) \cup-\operatorname{int}(\mathcal{K}) \Longleftrightarrow x_{0}^{2}>\|\bar{x}\|^{2}$.
(PR5) We say that the vectors $x$ and $y$ operator commute if they share a Jordan frame, that is,

$$
x=\lambda_{1} c_{1}+\lambda_{2} c_{2}, \quad y=\omega_{1} c_{1}+\omega_{2} c_{2}
$$

for a Jordan frame $\left\{c_{1}, c_{2}\right\}$.
(PR6) The vectors $x$ and $y$ operator commute if and only if $\bar{x}=0$ or $\bar{y}=0$ or $\bar{x}=\alpha \bar{y}$ for some real number $\alpha$. Thus if $x \in \mathbb{R}^{n}$, then $x$ and $J x$ operator commute.
(PR7) If $\operatorname{det}(x)>0, \operatorname{det}(y) \geq 0$ and $x \circ y=0$, then $y=0$.
(PR8) Any two non-zero vectors $x$ and $y$ in $\mathcal{K}$ are orthogonal if and only if $y=\mu J x$ for some $\mu>0$. Thus, $x \in \mathcal{K}$ and $y \in \mathcal{K}$ are orthogonal if and only if $x \circ y=0$.
(PR9) Self-duality:

$$
\begin{aligned}
\mathcal{K} & =\left\{x \in \mathbb{R}^{n}: x^{T} y \geq 0 \quad \forall y \in \mathcal{K}\right\} . \\
\operatorname{int}(\mathcal{K}) & =\left\{x \in \mathbb{R}^{n}: x^{T} y>0 \quad \forall 0 \neq y \in \mathcal{K}\right\} .
\end{aligned}
$$

For more details, we refer to Tao [7]. The definition of $P$-property of a linear transformation with respect to the Jordan spin algebra is given below. For a discussion on $P$-property and its variants in a general symmetric cone, we refer to Gowda et al. [3].

Definition 2 ( $P$-property). We will say that an $n \times n$ matrix $M$ has the $P$-property on $\mathcal{K}$ if:


Example 1. If $S$ is an $n \times n$ matrix with $S(\mathcal{K}) \subseteq \mathcal{K}$, then $I-S$ has $P$-property on $\mathcal{K}$ if and only if $\rho(S)<1$. See [5].

Example 2. Let $a, b, \lambda$ and $c$ be such that

$$
a+|\lambda|>0, \quad \lambda \neq 0, \quad a>\lambda c, \quad a>0, \quad(c+\lambda)^{2}<4 a \quad \text { and } b \in \mathbb{R}
$$

Define $M:=\left[\begin{array}{lll}a & b & c \\ 0 & 1 & 0 \\ \lambda & 0 & 1\end{array}\right]$. Then $M$ has $P$-property on $\mathcal{K}$. See [6].
We record some basic results from Gowda et al. [3] which we will use without explicit mentioning.

Theorem 1. Let $M$ be an $n \times n$ matrix. Then the following are true:
(i) If $M$ has the GUS-property, then $M$ must have $P$-property on $\mathcal{K}$.
(ii) GUS and $P$-properties are not equivalent.
(iii) If $M$ has the $P$-property, then $\operatorname{det}(M)>0$.

## 2. Results

To find new characterizations for the GUS-property, we first derive certain linear algebraic properties of a matrix that has $P$-property on $\mathcal{K}$.

Lemma 1. If $M$ is an $n \times n$ matrix, then the following are true:
(i) If $\operatorname{det}(M)>0$, then $M J$ has a positive eigenvalue and $\operatorname{det}(M J) \neq 0$.
(ii) If $M$ has the $P$-property on $\mathcal{K}$, then the following are true.
(a) MJ has a positive eigenvalue and non-singular. Further, if $\tau$ is any positive eigenvalue of $M J$, then there exists $u \in \operatorname{int}(\mathcal{K})$ such that $\mathcal{N}\left(M_{\tau}\right)=\operatorname{span}\{u\}$.
(b) If $\alpha \in \mathbb{R}^{n}$ is an eigenvalue of $M J$, then $\mathcal{N}\left(M_{\alpha}\right) \cap \partial \mathcal{K}=\{0\}$.
(iii) Let $\tau>0$ be such that $\mathcal{N}\left(M_{\tau}\right)=\operatorname{span}\{u\}$ for some $u \in \operatorname{int}(\mathcal{K})$. Then $\mathcal{C}\left(M_{\tau}\right)=$ $\left\{M_{\tau} x: x \in \partial \mathcal{K}\right\}$.
(iv) Let $\tau>0$ be a positive eigenvalue of $M J$ such that $\mathcal{N}\left(M_{\tau}\right)=\operatorname{span}\{u\}$ for some $u \in \operatorname{int}(\mathcal{K})$. Assume that $M$ satisfy the following conditions
(a) If $\alpha \in \mathbb{R}$ is an eigenvalue of $M J$, then $\mathcal{N}\left(M_{\alpha}\right) \cap \partial \mathcal{K}=\{0\}$.
(b) $y^{T} M y \geq 0 \forall y \in \partial \mathcal{K}$.

Then there exists $v \in \operatorname{int}(\mathcal{K})$ such that $\mathcal{N}\left(M_{\tau}^{T}\right)=\operatorname{span}\{v\}$.
Proof. First we prove (i). As $\operatorname{det}(M)>0$ and $J$ is non-singular, $\operatorname{det}(M J) \neq 0$. Define $f:[0, \infty) \rightarrow \mathbb{R}$ by $f(s):=\operatorname{det}(M-s J)$. Since $\lim _{s \rightarrow \infty} \frac{f(s)}{s^{n}}=\operatorname{det}(-J)<0$ and $f(0)>0$, by intermediate value theorem, there exists $s^{\prime} \in \mathbb{R}$ such that $f\left(s^{\prime}\right)=0$. As $J^{2}=I$, $f\left(s^{\prime}\right)=\operatorname{det}\left(M J-s^{\prime} I\right)=\operatorname{det}\left(M-s^{\prime} J\right) \operatorname{det}(J)=0$ and hence, $s^{\prime}>0$ is a positive eigenvalue of $M J$. This proves (i).

Now we prove (ii). Assume that $M$ has $P$-property on $\mathcal{K}$. Then $\operatorname{det}(M)>0$ and therefore by $(\mathrm{i}), \operatorname{det}(M J) \neq 0$ and has a positive eigenvalue, say $\tau$. Let $0 \neq v \in \mathbb{R}^{n}$ be an eigenvector of $M J$ and $w:=J v$. As $J^{2}=I$, we get $M w=\tau J w$, i.e., $M_{\tau} w=0$. We claim that $\operatorname{det}(w)>0$. By assuming $\operatorname{det}(w) \leq 0$, we get a contradiction. If $\operatorname{det}(w)<0$, then by spectral decomposition, we can write $w=\alpha e_{1}-\beta e_{2}$, where $\alpha>0$ and $\beta>0$. The vectors $w$ and $J w$ operator commute. So, $w$ and $M w$ operator commute. Since $J e_{1}=\mu e_{2}$ for some $\mu>0$, we see that

$$
J w=\alpha J e_{1}-\beta J e_{2}=\alpha \mu e_{2}-\beta\left(\frac{1}{\mu}\right) e_{1} .
$$

By distributive law,

$$
w \circ M w=-\tau \alpha \beta\left(\frac{e_{1}}{\mu}+\mu e_{2}\right)
$$

Thus, $w \circ M w \in-\operatorname{int}(\mathcal{K})$. Since $M$ has the $P$-property, $w=0$ and this is possible only when $v=0$, which is a contradiction. Let $\operatorname{det}(w)=0$. Then $M w=\tau J w$ and by using (PR4) and (PR8) we get $w \circ M w=0$. Since $M$ has the $P$-property, $w=0$ and thus $v=0$, which is a contradiction. Therefore, $\operatorname{det}(w)>0$. To this end, we have shown that if $u \in \mathcal{N}\left(M_{\tau}\right)$, then $\operatorname{det}(u)>0$, i.e., $\pm u \in \operatorname{int}(\mathcal{K})$. We now show that nullity $\left(M_{\tau}\right)=1$. If nullity $\left(M_{\tau}\right)>1$, then there exist linearly independent vectors $x$ and $y$ in $\mathcal{N}\left(M_{\tau}\right)$ such that $x^{T} y=0$. Since $\operatorname{det}(x)>0$ and $\operatorname{det}(y)>0$, by self-duality (PR9), either $x^{T} y>0$ or $x^{T} y<0$. So, $x$ and $y$ cannot be orthogonal. Thus, nullity $\left(M_{\tau}\right)=1$ and this proves (ii) (a).

If $x \in \mathcal{N}\left(M_{\alpha}\right) \cap \partial \mathcal{K}$, then $M x=\alpha J x$ and $x \in \partial \mathcal{K}$ and hence $x \circ M x=0$. Since $M$ has the $P$-property, $x=0$. This completes the proof of (ii)(b).

We now prove (iii). Let $v \in \operatorname{int}(\mathcal{K})$ be such that $\mathcal{N}\left(M_{\tau}\right)=\operatorname{span}\{v\}$. Suppose $w \in$ $\mathcal{C}\left(M_{\tau}\right)$. Then, $w=M_{\tau} z$ for some $z \in v^{\perp}$. Since $z$ is orthogonal to a vector in $\operatorname{int}(\mathcal{K})$, $\operatorname{det}(z)<0$. As $\operatorname{det}(v)>0$, by continuity, there exists $0<\alpha<1$ such that $\operatorname{det}((1-$ $\alpha) v+\alpha z)=0$. Define $y:=(1-\alpha) v+\alpha z$. Since $y^{T} v>0$ and $\operatorname{det}(y)=0, y \in \partial \mathcal{K}$. If $x:=\frac{y}{1-\alpha}=v+\frac{\alpha}{1-\alpha} z$, then we have

$$
M_{\tau} x=\frac{\alpha}{1-\alpha} M_{\tau} z \text { and } x \in \partial \mathcal{K}
$$

Thus, $w=M_{\tau}\left(\frac{1-\alpha}{\alpha} x\right)$. The proof of (iii) is complete.
We now prove (iv). By our assumption nullity $\left(M_{\tau}\right)=1$ and hence $\operatorname{nullity}\left(M_{\tau}^{T}\right)=1$. Let $\mathcal{N}\left(M_{\tau}^{T}\right)=\operatorname{span}\{x\}$. To complete the proof, by (PR4), it suffices to show that $\operatorname{det}(x)>0$. Suppose $\operatorname{det}(x)<0$. By (PR3), there exist $\lambda_{1}>0$ and $\lambda_{2}>0$ such that $x=\lambda_{1} e_{1}-\lambda_{2} e_{2}$, where $\left\{e_{1}, e_{2}\right\}$ is a Jordan frame. Define $p:=\frac{1}{\lambda_{1}} e_{1}+\frac{1}{\lambda_{2}} e_{2}$. Then, $p \in \operatorname{int}(\mathcal{K})$ and $p^{T} x=0$. Since $\mathcal{C}\left(M_{\tau}\right)=\left\{y: y^{T} x=0\right\}$, it follows that $p \in \mathcal{C}\left(M_{\tau}\right)$. By (iii), there exists $0 \neq y \in \partial \mathcal{K}$ such that $M_{\tau} y=M y-\tau J y=-p$; hence $y^{T} M y+p^{T} y=0$. Since $p \in \operatorname{int}(\mathcal{K})$ and $y \in \partial \mathcal{K}, p^{T} y>0$. As $y^{T} M y \geq 0, y^{T} M y+p^{T} y>0$. This is a contradiction. Thus, $\operatorname{det}(x) \geq 0$. Suppose $\operatorname{det}(x)=0$. Without loss of generality, assume $x \in \partial \mathcal{K}$. As $J x$ is orthogonal to $x,-J x \in \mathcal{C}\left(M_{\tau}\right)$. By (iii), we can find $y \in \partial \mathcal{K}$ such that $M_{\tau} y=-J x$, i.e., $M y-\tau J y=-J x$. Since $y^{T} J y=0$, we get $y^{T} M y+y^{T} J x=0$. As $y^{T} M y \geq 0$ and $y^{T} J x \geq 0$, it follows that $y^{T} J x=0$ and $y^{T} M y=0$. So, $y=\alpha x$ for some $\alpha>0$. From $M_{\tau} y=-J x$, we see that $M x=\rho J x$ for some $\rho \in \mathbb{R}$ and hence $x \in \mathcal{N}\left(M_{\rho}\right) \cap \partial \mathcal{K}$. By our assumption on $M$, we deduce that $x=0$, which is a contradiction. Therefore $\operatorname{det}(x)>0$. This proves (iv).

### 2.1. Necessary and sufficient conditions for GUS-property

We now prove our main result regarding the global uniqueness of solutions in secondorder cone linear complementarity problems by establishing a precise interconnection between the $P$ and GUS-properties in SOLCP. We first note a useful result that follows easily from Theorem 2 in [8] and Lemma 1.

Theorem 2. Let $M$ be an $n \times n$ matrix. Then $M$ has the GUS-property if and only if $M$ satisfies the following conditions:
(Z1) MJ is non-singular and has a positive eigenvalue.
(Z2) There exist $\tau>0$ and $v \in \operatorname{int}(\mathcal{K})$ such that $M J v=\tau v$. Further, all positive eigenvalues of $M J$ are equal to $\tau$ and $\operatorname{rank}(M J-\tau I)=n-1$.
(Z3) If $\alpha \in \mathbb{R}$, then $\mathcal{N}\left(M_{\alpha}\right) \cap \partial \mathcal{K}=\{0\}$.
(Z4) For all $y \in \partial \mathcal{K}, y^{T} M y \geq 0$ and $y^{T} M^{-1} y \geq 0$.

Proof. Assume that $M$ has the GUS-property. Since $P$-property on $\mathcal{K}$ is a necessary condition for GUS, by Lemma 1, we get (Z1) and (Z3). (Z2) and (Z4) are immediate from Theorem 2 in [8].

We now prove the converse. By Theorem 2 in [8], it suffices to show that there exists $v \in \operatorname{int}(\mathcal{K})$ such that $\mathcal{N}\left(M_{\tau}^{T}\right)=\operatorname{span}\{v\}$. But this is immediate from item (iv) of Lemma 1. This completes the proof.

Theorem 3. Let $M$ be an $n \times n$ matrix. Then the following are equivalent:
(T1) $M$ has the GUS-property.
(T2) $M$ satisfies the following:
(P1) $M$ has the P-property on $\mathcal{K}$.
(P2) For all $x \in \partial \mathcal{K}, x^{T} M x \geq 0$ and $x^{T} M^{-1} x \geq 0$.
(T3) $M$ satisfies the following:
(R1) $M^{T}$ has the P-property on $\mathcal{K}$.
(R2) For all $x \in \partial \mathcal{K}, x^{T} M x \geq 0$ and $x^{T} M^{-1} x \geq 0$.
(T4) $M^{T}$ has the GUS-property.
(T5) $M$ satisfies the following:
(S1) Both $M$ and $M^{T}$ have P-property.
(S2) For all $x \in \partial \mathcal{K}, x^{T} M x \geq 0$ and $x^{T} M^{-1} x \geq 0$.

Proof. We first show that $(\mathrm{T} 1) \Longrightarrow(\mathrm{T} 2)$. Since GUS implies $P$-property, we get (P1). By Theorem 2(Z4), (P2) must be true. Thus, (T1) $\Longrightarrow(\mathrm{T} 2)$.

To prove $(\mathrm{T} 2) \Longrightarrow(\mathrm{T} 1)$, we verify all four conditions in Theorem 2. Item $(\mathrm{Z} 4)$ in Theorem 2 follows immediately from (P2). By the $P$-property of $M$, $\operatorname{det}(M)>0$ and hence by Lemma 1(i), $M J$ is non-singular and has a positive eigenvalue. Thus, $M$ satisfies (Z1). Further, (Z3) is immediate from Lemma 1(ii)(b). We now verify (Z2). If $\tau>0$ is a positive eigenvalue of $M J$, then from Lemma 1 (ii)(a), there exists $v \in \operatorname{int}(\mathcal{K})$ such that $\mathcal{N}\left(M_{\tau}\right)=\operatorname{span}\{v\}$. To complete the proof, we need to show that all the positive eigenvalues of $M J$ are equal and $\operatorname{rank}(M J-\tau I)=n-1$. Suppose there exist distinct
positive eigenvalues of $M J$ (say, $\tau$ and $\tau^{\prime}$ ), such that $\tau^{\prime}=\tau+c$, where $c>0$. Let $x, y \in \operatorname{int}(\mathcal{K})$ be such that

$$
M J x=\tau x \text { and } M J y=\tau^{\prime} y
$$

Now we can find scalars $\alpha$ and $\beta$ such that $0 \neq u:=\alpha x+\beta y \in \partial \mathcal{K}$ and $\alpha \beta<0$. Consider the following two possibilities:
(A) $\alpha>0$ and $\beta<0$.
(B) $\alpha<0$ and $\beta>0$.

Assume (A). Since

$$
M J(\alpha x)=\tau \alpha x \text { and } M J(\beta y)=(\tau+c) \beta y
$$

we get $M J u=\tau u+c \beta y$. By (P2), $(J u)^{T} M J u \geq 0$. Further, $u^{T} J u=0$. Hence, $c \beta y^{T} J u \geq$ 0 . Since $y \in \operatorname{int}(\mathcal{K})$ and $u \in \partial \mathcal{K}$, we have $y^{T} J u>0$ and from $c>0$ and $\beta<0$, we have $c \beta y^{T} J u<0$ which is a contradiction. Thus (A) is not true. Now assume (B). Let $\theta^{\prime}>0$ be such that

$$
\frac{1}{\tau^{\prime}}+\frac{1}{\theta^{\prime}}=\frac{1}{\tau}
$$

From the equations

$$
M^{-1} y=\frac{1}{\tau^{\prime}} J y \quad \text { and } \quad M^{-1} x=\frac{1}{\tau} J x
$$

we find that

$$
M^{-1} u=\frac{1}{\tau^{\prime}} \alpha J u+\frac{1}{\theta^{\prime}} \alpha J x .
$$

Since $u^{T} M^{-1} u \geq 0$, we have

$$
\frac{1}{\theta^{\prime}} \alpha u^{T} J x \geq 0
$$

Since $x \in \operatorname{int}(\mathcal{K}), u \in \partial \mathcal{K}, \theta^{\prime}>0$ and $\alpha<0$, we see that $\frac{1}{\theta^{\prime}} \alpha u^{T} J x<0$. Thus (B) leads to a contradiction. Hence all the positive eigenvalues of $M J$ are equal. Suppose $\tau>0$ is the positive eigenvalue of $M J$. From Lemma 1(ii)(a), we see that nullity $\left(M_{\tau}\right)=1$ and hence $\operatorname{rank}\left(M_{\tau}\right)=n-1$. Since $J^{2}=I, \operatorname{rank}\left(M_{\tau}\right)=\operatorname{rank}(M J-\tau I)=n-1$. Thus $M$ satisfies (Z2). Hence, $M$ satisfies all sufficient conditions in Theorem 2. The proof of $(\mathrm{T} 2) \Longrightarrow(\mathrm{T} 1)$ is now complete.

By Corollary 2 in [8], $M$ has the GUS-property if and only if $M^{T}$ has GUS-property. Therefore (T1), (T2), (T3), (T4) and (T5) are equivalent.

We have seen that $M$ has the GUS-property if and only if $M^{T}$ has GUS. Here is an example of a matrix that has $P$-property on $\mathcal{K}$ while its transpose does not posses the $P$-property.

Example 3. Let

$$
\alpha:=\sqrt{\sqrt{2}+2} \text { and } \beta:=\sqrt{2(\sqrt{2}+1)} .
$$

Define

$$
M:=\left[\begin{array}{rrr}
1 & \alpha & 1 \\
0 & 1 & 0 \\
-1 & 0 & 1
\end{array}\right] \text { and } x:=\left[\begin{array}{c}
\sqrt{2}+1 \\
-\beta \\
-1
\end{array}\right] .
$$

Then

$$
M^{T} x=\left[\begin{array}{c}
2+\sqrt{2} \\
2 \sqrt{\sqrt{2}+1} \\
\sqrt{2}
\end{array}\right]
$$

By (PR6) in Section 2, $x$ and $M^{T} x$ operator commute. Further, $x \circ M^{T} x=0$. So, $M^{T}$ does not have the $P$-property. However, $M$ has the $P$-property (see Example 2).

## 2.2. $\mathbf{Z}$-Transformations

We now consider an interesting class of linear transformations namely Z-transformations over the second-order cone.

Definition 3. An $n \times n$ matrix $M$ is called a Z-matrix on $\mathcal{K}$ if the following condition is satisfied:

$$
x \in \mathcal{K}, \quad y \in \mathcal{K} \text { and } x^{T} y=0 \quad \Longrightarrow \quad y^{T} M x \leq 0
$$

It is well-known that if a matrix $S$ satisfies $S(\mathcal{K}) \subseteq \mathcal{K}$, then $I-S$ is a Z-matrix. Thus the class of $\mathbf{Z}$-matrices is very broad. If $M$ is a $\mathbf{Z}$-matrix on $\mathcal{K}$, then $\operatorname{SOLCP}(M, q)$ has a solution for all $q \in \mathbb{R}^{n}$ if and only if every eigenvalue of $M$ (over the complex field) has a positive real part, i.e., $M$ is positive stable. We refer to [5] for the proof of this result and more details on $\mathbf{Z}$-matrices. For $\mathbf{Z}$-matrices on $\mathcal{K}$, the following is conjectured in Tao [6]: For a $\mathbf{Z}$-matrix $M$ on $\mathcal{K}$, the following are equivalent: $M$ has the GUS-property if and only if $M$ has the $P$-property and $M$ is positive semidefinite on $\partial \mathcal{K}$. We prove this result now.

Theorem 4. Let $M$ be a Z-matrix on $\mathcal{K}$. Then the following are equivalent:
(A) $M$ has the GUS-property.
(B) $M$ is positive stable and $x^{T} M x \geq 0$ for all $x \in \partial \mathcal{K}$.

Proof. We first prove $(\mathrm{A}) \Longrightarrow(\mathrm{B})$. By our assumption $\operatorname{SOLCP}(M, q)$ has a unique solution for all $q \in \mathbb{R}^{n}$. From Theorem 7 in [5], we see that $M$ is positive stable if and only if $\operatorname{SOLCP}(M, q)$ has a solution for all $q \in \mathbb{R}^{n}$. Hence $M$ is positive stable. By Theorem $3, x^{T} M x \geq 0$ for all $x \in \partial \mathcal{K}$. This proves $(\mathrm{A}) \Longrightarrow(\mathrm{B})$.

We now prove $(\mathrm{B}) \Longrightarrow(\mathrm{A})$. By Theorem 13 in [5], $M$ has the $P$-property on $\mathcal{K}$. Further, by Theorem 7 in [5], $M$ has the $P$-property on $\mathcal{K}$ if and only if $M^{-1}(\mathcal{K}) \subseteq$ $\mathcal{K}$. Therefore, $x^{T} M^{-1} x \geq 0$ for all $x \in \mathcal{K}$. By Theorem 3, we see that $M$ has the GUS-property. This completes the proof.

We conclude the paper with the following example where $M$ and $M^{T}$ have $P$-property, but $M$ does not have the GUS-property.

Example 4. For $\alpha>0$, let

$$
M_{\alpha}:=\left[\begin{array}{ccc}
1-\alpha & -\alpha & 0 \\
\alpha & 1+\alpha & 0 \\
0 & 0 & 1
\end{array}\right] .
$$

Then $M_{\alpha}=I-S_{\alpha}$, where

$$
S_{\alpha}=\left[\begin{array}{ccc}
\alpha & \alpha & 0 \\
-\alpha & -\alpha & 0 \\
0 & 0 & 0
\end{array}\right]
$$

By an easy verification, $S_{\alpha}(\mathcal{K}) \subseteq \mathcal{K}$. Hence for any $\alpha>0, M_{\alpha}$ is a Z-matrix on $\mathcal{K}$. Since $S_{\alpha}{ }^{2}=0, \rho\left(S_{\alpha}\right)=0$. Thus, $M_{\alpha}$ and $M_{\alpha}^{T}$ have $P$-property on $\mathcal{K}$ for any $\alpha$. If $y \in \partial \mathcal{K}$, then it is easy to see that $y^{T} M_{\alpha} y=2 y_{1}^{2}-\alpha\left(y_{1}^{2}+y_{2}^{2}\right)$. If $\alpha>2$ and $y=(1,0,1)$ then $y^{T} M_{\alpha} y<0$. Hence for $\alpha>2, M_{\alpha}$ does not have the GUS-property.

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